# Fusing Satellite-Derived Irradiance and Point Measurements through Optimal Interpolation GC51C-1170

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#### Summary

- Motivation: Accurate irradiance estimates are needed for resource assessment, real-time estimates of PV power generation, and forecasts of PV power generation.
- Idea: Combine satellite derived irradiance estimates over a large area with sparse, accurate irradiance measurements though optimal interpolation.
- **Results:** Optimal interpolation reduces root mean square error (RMSE) by up to 50% and nearly eliminates mean bias error (MBE).

#### Essentials of optimal interpolation

Suppose a model suggests that irradiance outside is ~900 W/m<sup>2</sup> and a sensor measures the irradiance to be ~850 W/m<sup>2</sup>. How can you optimally combine these two pieces of information?

- Call your estimated value  $x_h$  and the measurement y.
- The error variances,  $\sigma_v^2$  and  $\sigma_b^2$ , measure how large of an error you expect from each estimate.
- Optimal interpolation (equivalent to least squares) is the best, linear, unbiased estimate of the true value.
- The optimal interpolation result (known as the analysis) is given by:





## Satellite and ground data

- Data are derived from two sources, geostationary satellite images and ground irradiance measurements from sensors and PV cells.
- Optimal interpolation enables accurate but sparse ground data to improve the irradiance estimate over a large area (in this case, Tucson).





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## Optimal interpolation with satellite data

We remove the effects of time of day, time of year and unit of measurement by converting sensor and PV data to a clear sky index. done by dividing the İS measured irradiance or power production by the irradiance or power production under a clear sky.







- C is the satellite correlation matrix. Points in the background are more correlated if they have a similar visible satellite image pixel value. For example, if two points have a similar pixel value in the visible satellite image the clouds over the two points will likely have similar properties.
- D is the background error variance. It describes how far from the truth one can expect the background irradiance estimate to stray.
- P and R are the satellite and sensor error covariance matrices. If we know the error at one location this will tell us what to expect at others.
- **R** is a diagonal matrix because we expect the *error* correlation between sensors to be negligible.
- H maps points in the satellite image to sensors on the ground.
- W is the weight matrix. The larger the weight the more we trust our ground observations.
- Parameters for calculating C and D (including the correlation variable and inflation parameter) have been optimized over a tuning dataset.

Visible satellite images are converted to semi-empirical model (SE). The measurements, y, with this background

#### Results

- Errors are calculated for sensors not included in the OI routine for 3 months of data
- MBE is nearly eliminated for both satellite models
- After OI, the two models have similar RMSE
- RMSE has decreased by nearly 50% for the SE model
- Scatterplots of predicted vs measured GHI and clear-sky index further illustrate the improvements of the analysis (after OI) over the background (before OI)



#### Future work

- forecasts.





Combine satellite images with a numerical cloud advection model and ground irradiance measurements using a Kalman filter in order to create

Determine the feasibility of using sensors in Tucson to improve satellite estimates 100 miles away when weather patterns allow.